

Installation Guide

For Electric Retractable Thruster Models SR-L&V130, SR-L&V170, SRV210, SRV250



DOCUMENT ID: 2882 REVISION: 20 DATE: 2024

LANGUAGE: EN



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Accidental activation of the retract mechanism can cause serious injury due to the high-pressure force used for closing the hatch. IF operating the hatch during any work/ maintenance around or inside the retract hatch, USE CAUTION.

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MC_0020

General:

- The installer must read this document to ensure necessary familiarity with the product before installation.
- Directions outlined in this document cannot be guaranteed to comply with all international and national regulations, including but not limited to health and safety procedures. It is the installer's responsibility to adhere to all applicable international and national regulations when installing Sleipner products.
- This document contains general installation guidelines intended to support experienced installers. Contact professional installers familiar with the vessel and applicable regulations if assistance is required.
- If local regulation requires any electrical work to be performed by a licensed professional, seek a licensed professional.
- · When planning the installation of Sleipner products, ensure easy access to the products for future service and inspection requirements.

Responsibility of the installer

MC_0440

For retract thrusters:

- The installation position of stern-mounted retract thrusters must not conflict with the propulsion propellers or their water trail. (NB: consult a naval architect for an exact position.)
- Paint inside the retract housing with anti-fouling. (NB: Do not paint the drive shaft.)

For Sleipner thruster systems:

C 0425

- Do not install the thruster system in any position that requires modifying the stiffener/ stringer/ supports, which may jeopardize the hull integrity. Consult with the boat builder to see if this can be done safely if absolutely necessary.
- Never run the thruster out of water without load. Without load or resistance, the thruster propeller RPM will reach extremely high speed, damaging the system.

For on-board electric motor driven systems:

MC 0031

- Ensure motors installed in small compartments are dry and well-ventilated to allow the electric motor to cool.
- The electric motor, components, and cables must be mounted to remain dry.
- The electric motor can reach over 100°C before activating the temperature switch. Any loose items near the thruster motor are a potential fire hazard and can cause short-circuiting.
- The thruster power supply circuit must include the recommended sized fuse and a battery isolation switch.

MC_0426

For DC electric motors:

 The electric motor will generate some carbon dust. Storage compartments must be separated from the thruster to prevent nearby items becoming dusty/ dirty. (NB: IP version motors generate dust but are enclosed.)

For lithium batteries for on/off thruster systems:

MC 0501

High capacity lithium batteries are capable of supplying a higher operating voltage to the motor than the on/off thrusters are rated for.
 Running thrusters at higher than rated voltage will reduce operating time, increase wear and damage the thruster. Operating the thruster outside specified ratings will void warranty.

For Sleipner S-Link™ systems:

MC_0105

- When installing an S-Link™ system, connect ONLY original Sleipner S-Link™ products or other authorized control equipment directly to the
 S-Link™ bus. When connecting non-authorized third-party equipment, it must always be connected through a Sleipner-supplied interface product.
- Any attempt to directly control or connect to the S-Link™ control system without a designated and approved interface from Sleipner will
 void all warranties and responsibilities of the connected Sleipner products. If you interface the S-Link™ bus by agreement with Sleipner
 through a designated Sleipner-supplied interface, you are still required to install at least one original Sleipner control panel to enable efficient
 troubleshooting if necessary.

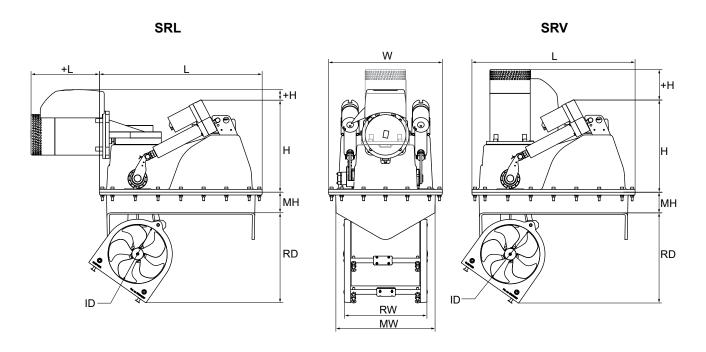
Do NOT remove the Red spacer block until the installation is completed.



Thruster measurements

			. 130		. 130	SRL170 24V		
Measurement	Measurement description	mm	inch	mm	inch	mm	inch	
+L	Motor supplementary measurement (Length)	264	10.39	269	10.59	289	11.38	
L	Thruster housing length	688	27.09	688	27.09	688	27.09	
+H	Motor supplementary measurement (Height)	49	1.92	30	1.18	58	2.28	
Н	Thruster housing height	389	15.31	389	15.31	389	15.31	
МН	Minimum flange height	97	3.8	97	3.8	97	3.8	
RD	Twist ring depth	374	14.72	374	14.72	374	14.72	
ID	Tunnel diameter	250	9.84	250	9.84	250	9.84	
W	SRF flange & thruster housing width	480	18.90	480	18.90	480	18.90	
RW	Tunnel width	348	13.70	348	13.70	348	13.70	
MW	Flange width	420	16.54	420	16.54	420	16.54	

			130		/130		170		7210		7250
Measurement	Measurement description	mm	inch	mm	inch	mm	inch	mm	inch	mm	inch
L	Thruster housing length	688	27.09	688	27.09	688	27.09	688	27.09	843	33.19
+H	Motor supplementary measurement (Height)	104	4.09	110	4.33	128	5.04	211	8.31	172	6.77
Н	Thruster housing height	389	15.31	389	15.31	389	15.31	389	15.31	452	17.80
МН	Minimum flange height	97	3.8	97	3.8	97	3.8	97	3.8	115	4.53
RD	Twist ring depth	374	14.72	374	14.72	374	14.72	374	14.72	454	17.9
ID	Tunnel diameter	250	9.84	250	9.84	250	9.84	250	9.84	300	11.81
W	SRF flange & thruster housing width	480	18.90	480	18.90	480	18.90	480	18.90	580	22.83
RW	Tunnel width	348	13.70	348	13.70	348	13.70	348	13.70	415	16.34
MW	Flange width	420	16.54	420	16.54	420	16.54	420	16.54	480	18.90



Thruster specifications

MC_0834

Product	Nominal Operating Voltage*	Thrust at stated o	operating voltage*	Power Output	Weight	Maximum Operation Time
SRL&V130 12V	10.5V	130kg / 284lbs (10.5V)	160kg / 352lbs (12V)	6.5kW / 8.7hp	82kg / 181lbs	
SRL&V130 24V	21V	130kg / 284lbs (21V)	160kg / 352lbs (24V)	6.5kW / 8.7hp	82kg / 181lbs	
SRL&V170 24V	21V	170kg / 374lbs (21V)	210kg / 462lbs (24V)	8kW / 11.8hp	88kg / 194lbs	S2 2-3 min. At 20°C ambient temperature
SRL&V210 24V	21V	210kg / 462lbs (21V)	250kg / 550lbs (24V)	10kW / 13.15hp	112kg / 247lbs	,
SRL&V250 24V	21V	250kg / 551lbs (21V)	300kg / 661lbs (24V)	11.4kW / 15.5hp	117kg / 257lbs	

^{*}Voltage measured at motor terminals when thruster is running

Hull specifications

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Use sealants, adhesives or bonding material compatible with the materials of your vessels hull and Sleipner product.

For information regards the material in Sleipner products, see table.

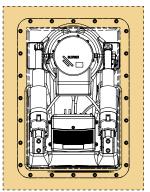
Product		Resin
Housing	SR(P)80/100	Polyester
Flange	SRF-185-GRP	Polyester
Flange	SRF-250-GRP	Polyester
Flange	SRF-300-GRP	Polyester
Flange	SRF-386-GRP	Polyester

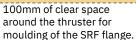
Positioning of the retract thruster

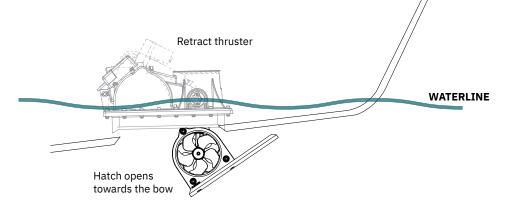
Retract Thruster

The thruster must always be installed so the hatch is opened towards the bow. Ensure enough space for the complete retract unit including room for installation of SRF flange and for future service.

Allow minimum 100mm of clear space around the thruster for moulding of the SRF flange. Ensure that when the thruster is deployed, the depth of the propeller exceeds the minimum tunnel depth defined in below table.

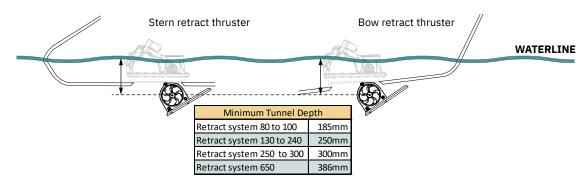






Installing the thruster below the waterline as outlined is important for two reasons:

- Avoid drawing air from the surface which will reduce performance and increase noise levels.
- To get as much water pressure as possible to achieve maximum thrust.

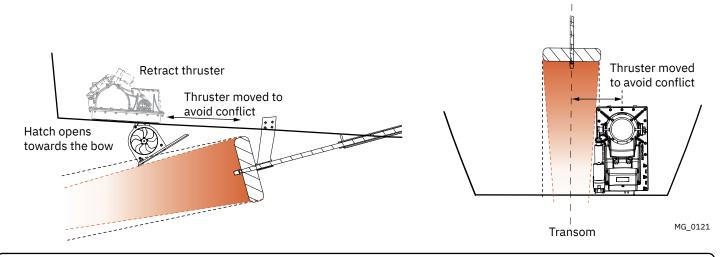


Bow installation

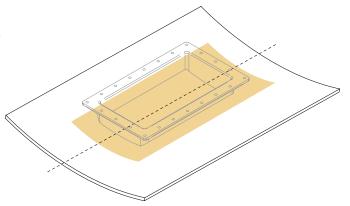
The thruster must be installed in the center line of the keel and as far forward as possible while following the minimum tunnel depth requirement.

Stern installation

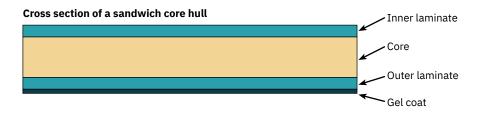
To avoid conflict between the thruster and propulsion propellers, trim tabs or rudders, the stern installation can be offset from the keel center line.



- Ensure to have a minimum of 100mm space around the thruster installation to have service access.
- Bow thrusters must be positioned on the boat center line.
- Stern thrusters can be positioned off the centre line.



For vessels with sandwich hull construction, additional reinforcement of the area around the SRF flange is required.



- To achieve maximum strength and bonding in the area around the installation of the SRF flange remove the inner laminate and core material to expose the outer laminate. Remove enough area for a 100mm (minimum) clearance surrounding the SRF flange. (Reference 1).
- Reinforce the area by applying several bonding layers to strengthen the hull for the operation of the retract thruster. (**Reference 2**).



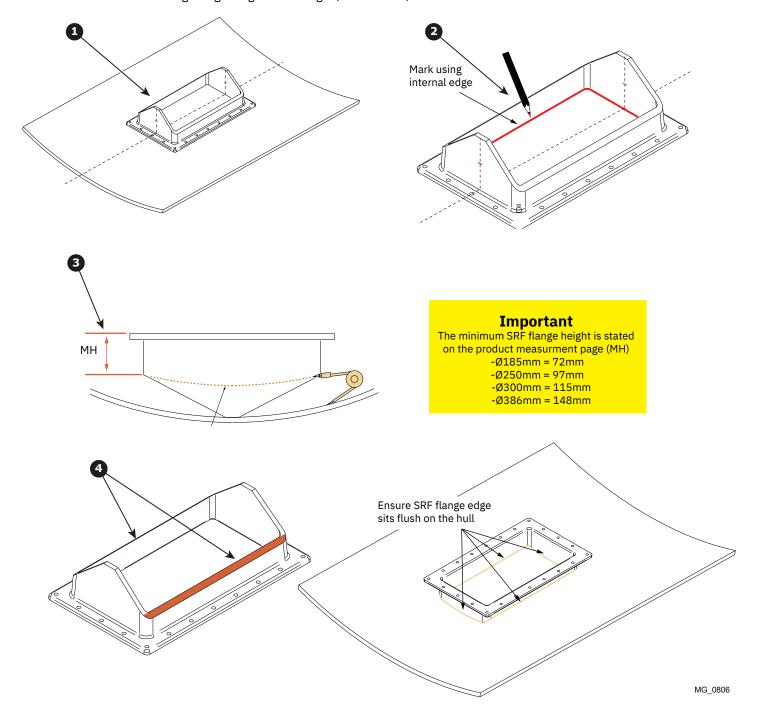


- Flip the SRF flange upside down and position it at the identified installation location. (Reference 1).
 - For bow thrusters, this is usually symmetrical about the vessel centerline.
 - For stern thrusters, the position of the thruster may deviate from centerline.
- Use the internal edge to mark were to cut out the thruster hatch from the hull. (Reference 2).
- The SRF flange must be adapted so that the two longitudal edges on the SRF flange run flush with the hull. To do so the SRF flange must be trimmed down to match the hull profile curvature. Use a suitable tool to mark the cutting line on the SRF flange. (Reference 3).

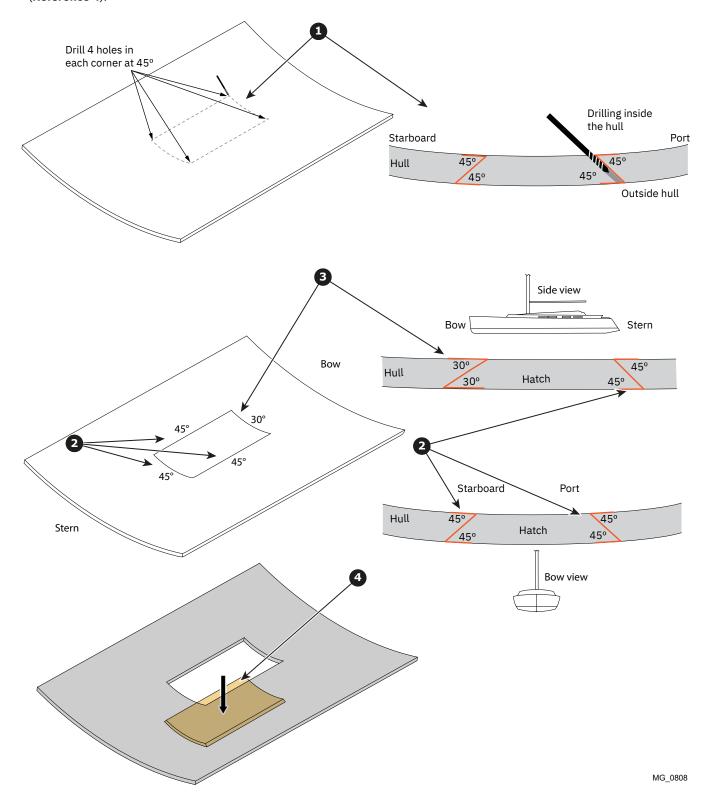
Important: The cutting line position must be according to the MH measurement for the actual thruster model. See table in topic "Thruster measurement".

For guidance or methods to transfer the hull profile to the SRF flange for cutting, consult a naval architect.

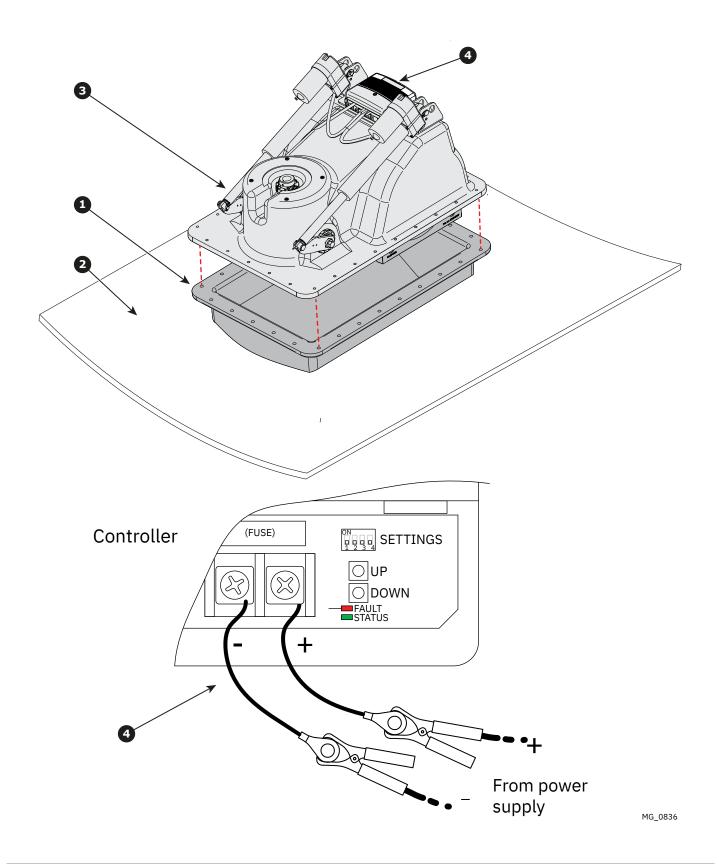
• DO NOT cut the SRF flange length edge at this stage. (Reference 4)



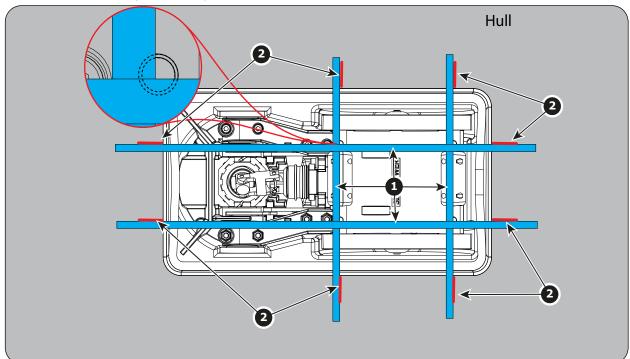
- When cutting from inside, prepare for cutting by drilling 4 holes in each corner of the marked area at 45° angle inwards against the centerline (**Reference 1**).
- The hatch opening must be cut at an angle of 45° on starboard, port and stern sides, (Reference 2), and 30° on the side facing the bow (Reference 3). This ensures that forces from water hitting the closed hatch is absorbed by the hull.
 NOTE: It is of great importance that these cutting angles are correct. Otherwise the hatch will jam during opening.
 Use a suitable cutting tool able to be set to the desired angle, e.g. a jigsaw.
- Remove the hatch from the hull. Prevent the hatch from falling down, ensure proper support to the hatch when cutting. (**Reference 4**).

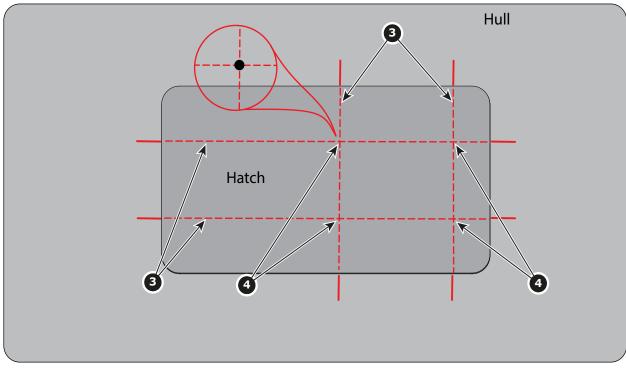


- Position the trimmed SRF flange (Reference 1) in the correct position over the hatch cut-out in the hull (Reference 2).
- Install the thruster housing (**Reference 3**) provisionally on the SRF flange, and secure it with 4 screws. Verify that the complete thruster assembly (SRF flange and thruster housing) is still inn correct position.
- Prepare two power supply cables from the retract controller (Reference 4). Do not connect to the power supply yet.



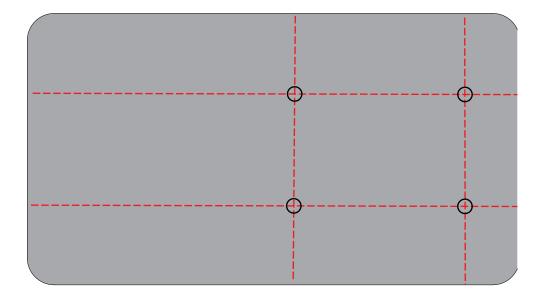
- Ensure that the SRF flange and the thruster housing are positioned correctly inside the hull. (See the previous topic).
- Use a suitable aid, e.g. adhesive tape, straight edge, laser or other adequate aid to follow a straight line over the center of the hatch bolt holes, in two directions. (**Reference 1, and detail bubble**).
- Apply marks on the hull, at the edges of the used aid, on the side facing the center of the bolt holes. (Reference 2)
- Remove the adhesive tape (or other used aid).
- Position the pre-cut hatch in the opening in the hull, and support it in its position.
- Use a flexible ruler or similar to draw extended lines on the hatch, between the marks created on the hull. (Reference 3).
- The correct position of the hatch attachment holes are now in the intersection of the extended lines on the hatch. Make a mark in each intersection (**Reference 4**).





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- Drill four Ø11mm holes in the center of each marking created in the previous step.
- It is recomended to use a pillar drill with a proper construction surface to ensure that the holes are drilled perpendicular to the hatch.
- · Countersunk the holes after drilling.



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Temporarily setting up the complete installation to ensure no conflicts during the final operation of the thruster.

- Temporarily attach the hatch to the thruster housing by using the M10 countersunk bolts through the drilled holes in the hatch and screw them in to the hatch bolt holes. (**Reference 1**).
 - NB: Ensure correct orientation for the thruster to open the hatch facing the bow. Remember attachment is for temporary checking of thruster operation only.
- Ensure that the hatch is in proper place (Reference 2).
- Connect the prepared power supply cables from the thruster controller to a power supply.
 (NB: Refer to the label on actuators for correct voltage)
- Set switch no. 4 on the DIP-switch marked "SETTINGS" to ON.
- Press "DOWN" to extend the tunnel and check the hatch opens fully without touching the hull. If the hatch is obstructed by the hull in the front, (**Reference 3**), the SRF flange must be adapted so that the hatch does no longer touch the hull when in open position. (**Reference 4**).
- If necessary:
 Grind the front and side egdes of the flange a necessary amount to obtain space between the hull and the hatch. (**Reference 5**).
 Note that the reference 5 illustration shows an excessive grind down in the shaded area to clarify the operation.
- Ensure that there is a space between the twist ring and the hatch during the grinding process. **Do not allow this space to be zero**. (**Reference 6**).

IMPORTANT

• If the space between the hull and the hatch is not obtained by the grinding process alone, (still with a space between the twist ring and the hatch), the flange must in addition be lifted in the aft end. Use wedges to obtain the correct height (**Reference 7**). When correct position is obtained, mark the wedge positions, and note the distance between the flange and the hull.

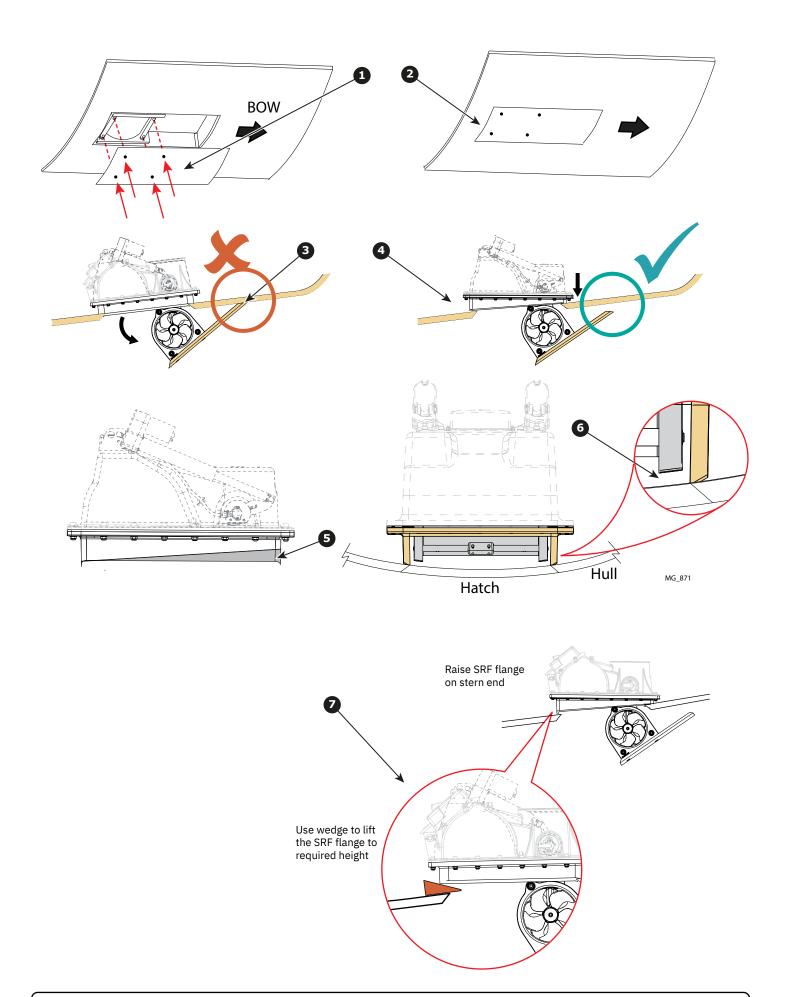
IMPORTANT

The hatch contact edges and the hull contact edges MUST work as the mechanical end stop. During cruising, slamming forces from the water must be absorbed by these areas, not the thruster.

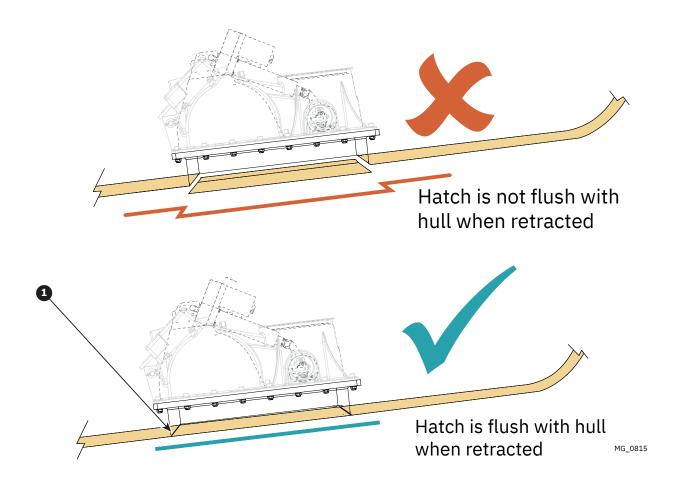


CAUTION.

Accidential activation of the retract mechanism can cause serious injury due to the high pressure force used for moving the hatch. Use caution when performing any work or maintenance around or inside the retract mechanism / hatch.

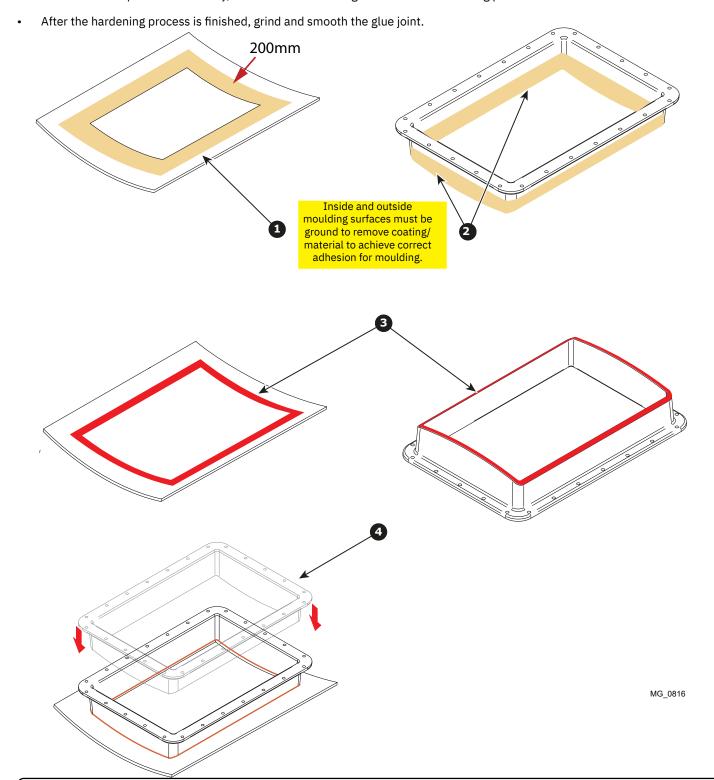


- Press "UP" to retract the tunnel.
- Ensure that the hatch is fitted in the hatch opening, and that the hatch is aligned flush with the hull at all edges. (**Reference 1**).
- Ensure that there is pressure on all the contact surfaces between the hatch and the hull when the hatch is closed.
- If the hatch is not closing with pressure on all the contact surfaces, the entire SRF flange must be raised to obtain this.
- When the thruster is operating as required, ensure that the position of the SRF flange can be recreated by adding position marks and leveling measurements.
- Remove the thruster housing from the SRF flange.

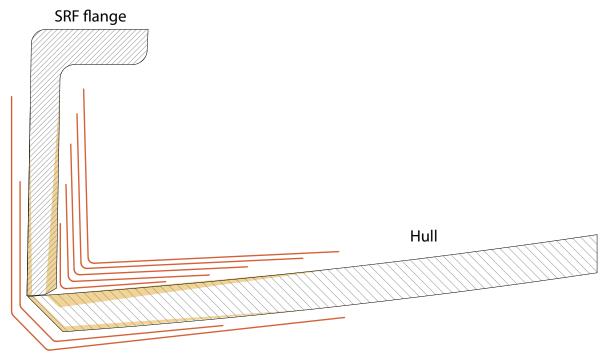


Before grinding of hull and SRF flange, precautions must be taken against grinding dust inside the boat. Surfaces to be moulded/bonded must be ground to remove coating and material to achieve sufficient adhesion.

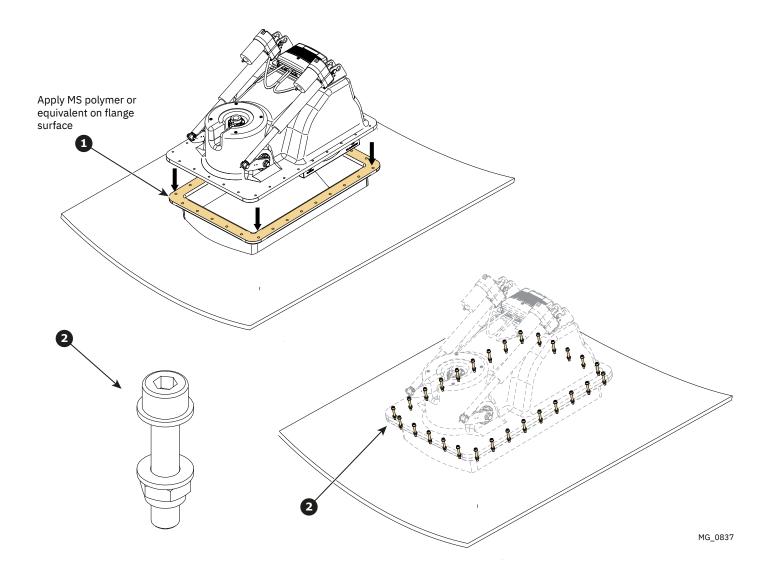
- Grind and smooth the area inside the hull opening to remove the gelcoat. Remove the gelcoat in a width of 200mm. (**Reference 1**).
- Grind the inside and outside of the SRF flange to remove the gelcoat (Reference 2).
- Apply appropriate glue / adhesive inside the hull opening and on the bottom of the SRF flange (Reference 3). Apply enough glue
 to fill the possible space between the raised SRF flange and the hull. Reinstall the wedges from the pre-install procedure if used
 to obtain the correct height in the aft end of the flange.
- Lower the SRF flange on to the hull, and position it according to the marks and measurement performed in the previous steps. (**Reference 4**).
- After the SRF is positined correctly, remove the excessive glue before the hardening process starts.



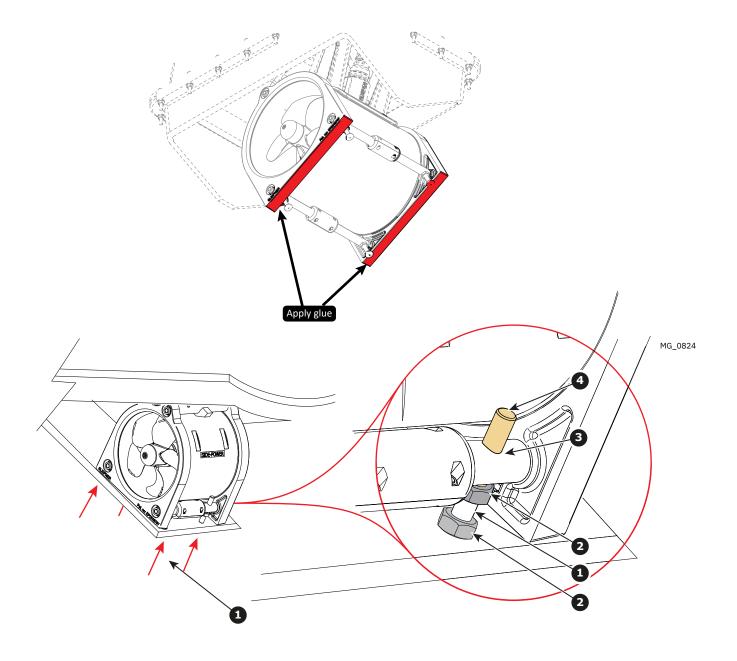
- After the glue / adhesive has hardened completely, the inside and outside of the SRF flange and hull must be laminated. Apply several layers of fibreglass and ensure that the resin and fibreglass is compatible with hull and flange materials.
- When the laminated ares has cured properly, smooth all moulded surfaces and apply coating.
- Apply putty before coating if necessary.



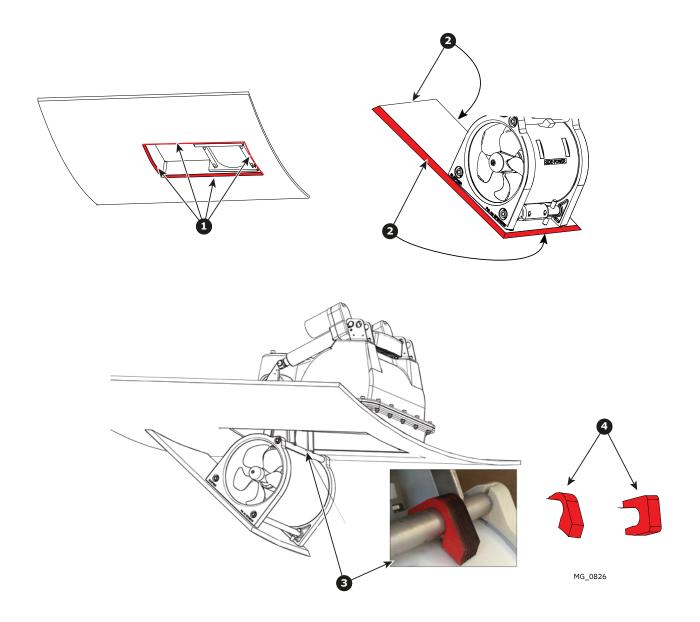
- When the lamination process is completed, the thruster housing can be installed.
- Apply MS polymer or equivalent on the SRF flange surface (**Reference 1**).
- · Lower the thruster housing down on the SRF flange.
- Install bolts, washers and nuts (**Reference 2**) in each mounting hole.
- NOTE: It may be necessary to insert two of the bolts from the underside of the SRF flange with the nut then on the top to avoid conflict with the position sensor.
 (For SR L&V 80 and 100 variants only).
- Tighten the bolts with a torque of 4Nm 2,9lb/ft. Start with a corner bolt, then continue tighten the bolts in a cross pattern.



- Ensure that the thruster is in the outer position
- Apply glue on the twist ring facing the hatch.
- Enter the hatch bolts through the hatch, (**Reference 1**) and enter the lock nuts (**Reference 2**) on the bolt. Position the nuts close to the inside of the hatch, but do not tighten.
- Enter the bolts in to the bolt holes in the thruster housing (**Reference 3**).
- Bolt the hatch to the tunnel. Ensure the bolts do NOT conflict with the tunnel. (Reference 4).
 (NB: Bolts can be cut, depending on hatch thickness.)
- When all four bolts are tightened so that the hatch is in tight connection to the twist rings, tighten the lock nuts (**Reference 2**) to the hatch and bolt holes in the tunnel housing respectively.
- Retract the thruster to verify that the movement is smooth, and that the hatch is in correct position when the thruster is in both open and closed position.



- Lower down the thruster.
- Apply a layer of aluminium or duct tape on hatch opening edges on the hull. (**Reference 1**). This is for masking out for the adhesive in the next step.
- Apply filler or equivalent to hatch edges in such amount that it will fill the gap between the hull and the hatch. (Reference 2).
- Operate the thruster to "IN" position. Smooth out the filler and add more if needed. After curing time, grind and smooth the surface. Apply glue on twist rings contact surface.
- Apply coating inside and outside of the hatch and on the hull to cover the fiberglass and filler.
- Remove the red spacer block located above the tunnel. (Reference 3). Note: Two types of spacer block is used. (Reference 4).



- Install the motor onto the motor bracket ensuring the couplings and the drive shafts have locked together. (Reference 1).

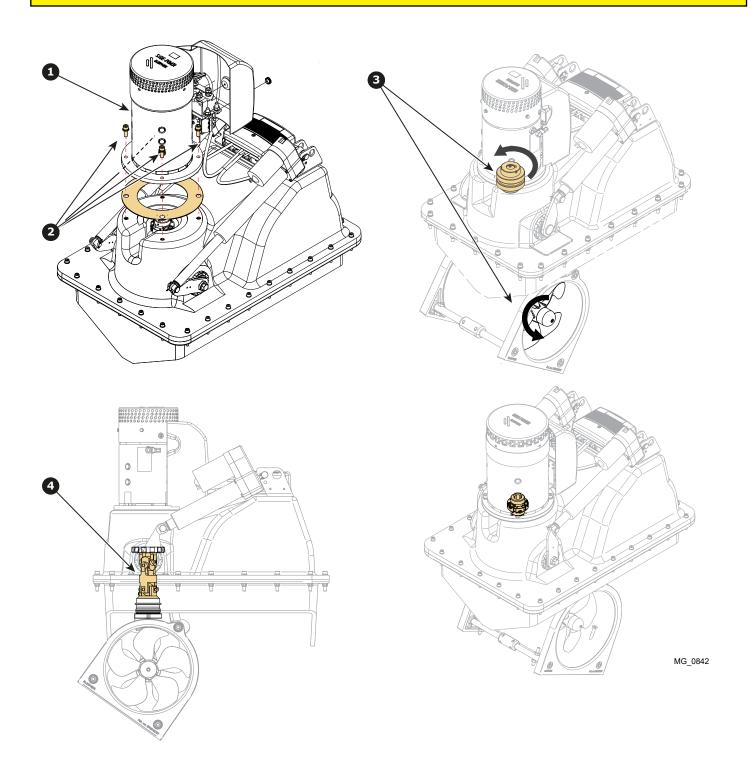
 NB: depending on your coupling you may need to wiggle the motor into place. Ensure the couplings are engaging correctly.

 Ensure the motor cable terminals are accessible for electrical installation later.
- Enter the bolts with washers holding the motor to the motor bracket. (Reference 2). Tightening torque 33Nm (24lb/ft)
- Check the drive shafts engage by rotating the propeller. (**Reference 3**). It is required the propeller can rotate via hand power. (**NB: Rotating the propellers can be hard because of the gear reduction and the motor.**)

 WARNING. The propeller blades may be sharp.
- Apply grease to the internal drive shaft. (Reference 4). We advise painting the gear house and propellers with anti-fouling. (NB: Do not paint the anodes, sealing, rubber fittings or propeller shafts)

(NB: The motor must be covered to avoid dust from fabrication/ maintenance operation entering the motor or the solenoids.

After fabrication maintenance operations have ceased the cover must be removed before operating the thruster.)



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- Install the motor onto the motor bracket ensuring the couplings and the drive shafts have locked together. (Reference 1).

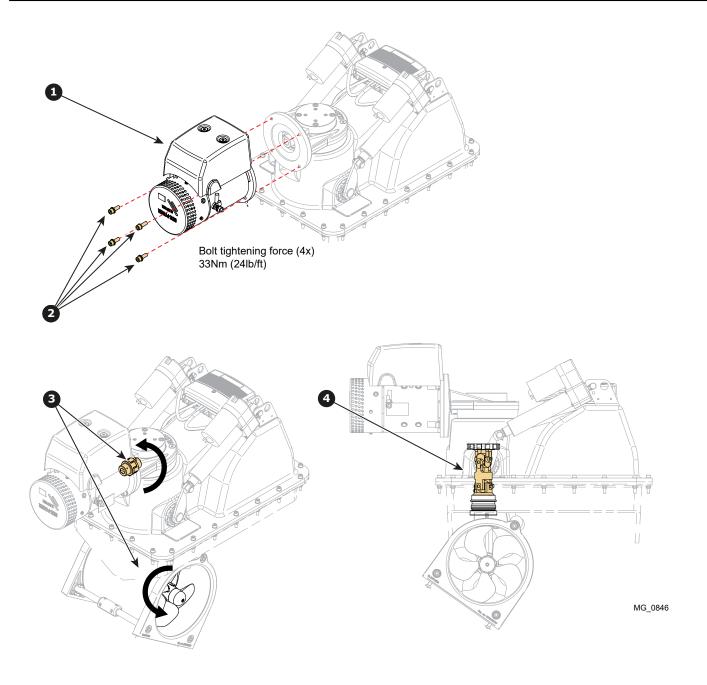
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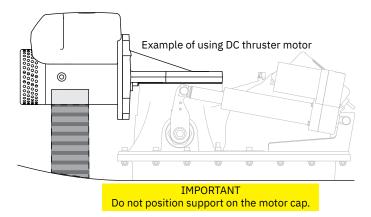
(NB: The motor must be covered to avoid dust from fabrication/ maintenance operation entering the motor or the solenoids.

After fabrication maintenance operations have ceased the cover must be removed before operating the thruster.)



Support for the motor

If you are installing the motor at an angle of more than 30 degrees off vertical, the motor will require separate/ additional support.



Plan the location of electrical components before starting with the electrical installation. Main electrical components will typically
consist of battery, fuse, main switch, Proportional Power Controller (PPC) and thruster motor, see Wiring Diagram chapter for an
overview.

Sleipner offers both manual main switches and Automatic Main Switches (AMS). Sleipner AMS is controlled by the control panel in addition to the option of manual operation. Turning on the control panel also turn on the automatic main switch. When the control panel is turned off the automatic main switch is turned off. This ensures that the control electronics and motor are only energized when the control panel is turned on. Sleipner offers AMS supporting either S-Link or ON/OFF control panels. Note that the AMS requires a separate power supply which should be protected by a dedicated fuse. Ensure to select an AMS with a voltage rating according to the chosen motor- and battery voltage.

Electrical products installed in gasoline engine spaces or other areas potentially exposed for explosive gases must be Ignition Protected. Products installed in such locations should conform to the ISO 8846, SAE J1171 or UL 1500 standard.

- 2. Estimate the total length of the power cables to determine the recommended cross-section. The total power cable length is defined as the distance from the positive battery terminal, via fuse, main switch, PPC, and thruster motor, and all the way back to the negative battery terminal.
- 3. Find the recommended power cable cross-section for the installation by using the estimated total power cable length and the table shown in the chapter Electrical Reference Guide.
- 4. Select the recommended fuse size by using the table shown in the chapter Electrical Reference Guide.
- 5. Use an appropriate dimensioned battery with Cold Cranking Amps (CCA) according to recommendations given in the Electrical Reference Guide chapter. Battery voltage must be compliant with the voltage rating of the thruster motor and control circuitry. The capacity and rated discharge current of the battery should be according to the rated nominal current drawn and the typical duty cycle for thruster operation. The nominal current drawn is listed in the Electrical Reference Guide chapter.

The actual voltage at the motor while running the thruster determines the motor RPM and thrust. Using a smaller cross-section than recommended or a low-capacity battery could reduce performance.

Installing a battery close to the thruster reduces the length of the power cables and potentially increases the performance, due to lower voltage drop in the power cables. For installations on large vessels with bow and stern thrusters or catamarans a dedicated battery for each thruster should be considered.

Install and connect the electrical components according to the applicable Wiring Diagram chapter.

For safety reasons it is always recommended to install a fuse and a main switch on the power cables and as close as possible to the positive battery terminal. The main switch must be installed such that it is easily accessible so that the thruster can be electrically disconnected to a safe state when not on-board or in the case of an emergency.

For dual thruster systems using only one battery bank a dedicated fuse and main switch should be installed for each thruster. These should be installed close to the battery bank.

Follow the instructions in the Motor Lug Connection chapter when fastening the power cables to the motor.



CAUTION

After all electrical connections have been completed, turn off main switch and check the following with an ohmmeter:

- 1. There is no electrical connection between electro-motor flange and the positive terminal on the motor.
- 2. There is no electrical connection between electro-motor flange and the negative terminal on the motor.

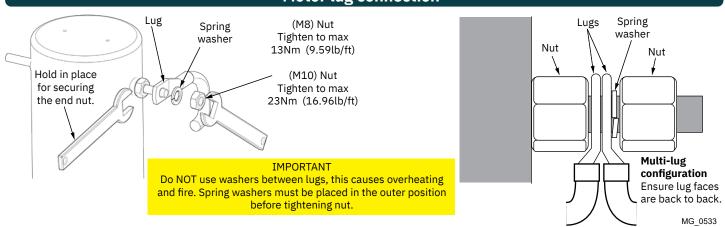
 If unsure contact skilled personnel.

Electrical reference guide

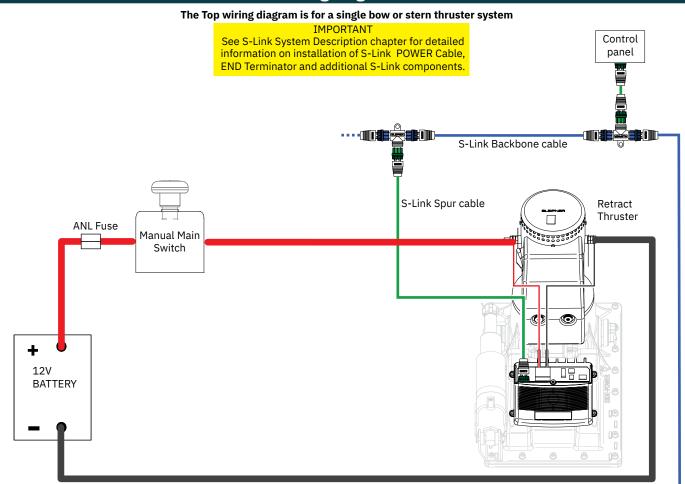
MC_0682

					Cross Section Guide for Power Cables																		
Model Size	System Voltage	Nominal current	Min. battery CCA	Rec. fuse	Unit	<7 total		7-1 total		15-: total	21m + & -	22-2 total		28-: total	35m + & -		45m + & -						
			331			Min.	Rec.	Min.	Rec.	Min.	Rec.	Min.	Rec.	Min.	Rec.	Min.	Rec.						
	40)/		DIN: 750	ANL	mm²	95	95	2 x 95	2 x 95	2 x 120	2 x 120	NIA	NIA			NA	N. A.						
120	12V	800 A	SAE: 760 EN: 680	500	AWG	3/0	3/0	2 x 2/0	2 x 2/0	2 x 4/0	2 x 4/0	NA	NA	NA	NA		NA						
130	24V	350 A	DIN: 400	ANL	mm2	50	50	50	70	70	95	95	120	120	2 x 70	2 x 95	2 x 95						
	24 V	330 A	350 A	330 A	330 A	330 A	330 A	SAE: 760 EN: 680		325	AWG	1/0	1/0	1/0	2/0	2/0	3/0	3/0	4/0	4/0	2 x 2/0	2 x 3/0	2 x 3/0
170	24V	550 A	DIN: 560 SAE: 1064	ANL	mm²	70	70	70	95	95	120	120	2 x 95	2 x 95	2 x 95	2 x 120	2 x 120						
170	24V	550 A	EN: 940	400	AWG	2/0	2/0	2/0	3/0	3/0	4/0	4/0	2 x 3/0	2 x 3/0	2 x 3/0	2 x 4/0	2 x 4/0						
210	24V	500 A	DIN: 560 SAE: 1064	ANL 400-	mm²	70	70	70	95	95	120	120	2 x 70	2 x 70	2 x 95	2 x 95	2 x 120						
210	24 V	500 A	EN: 940	500	AWG	2/0	2/0	2/0	3/0	3/0	4/0	4/0	2 x 2/0	2 x 2/0	2 x 3/0	2 x 3/0	2 x 4/0						
250	24V	610 670 A	DIN: 700		ANL	mm²	70	70	95	120	120	2 x 95	2 x 95	2 x 95	2 x 95	2 x 120	2 x 120	2 x 120					
250	24V	610-670 AS	EN: 1170	500	AWG	2/0	2/0	3/0	4/0	4/0	2 x 3/0	2 x 3/0	2 x 3/0	2 x 3/0	2 x 4/0	2 x 4/0	2 x 4/0						

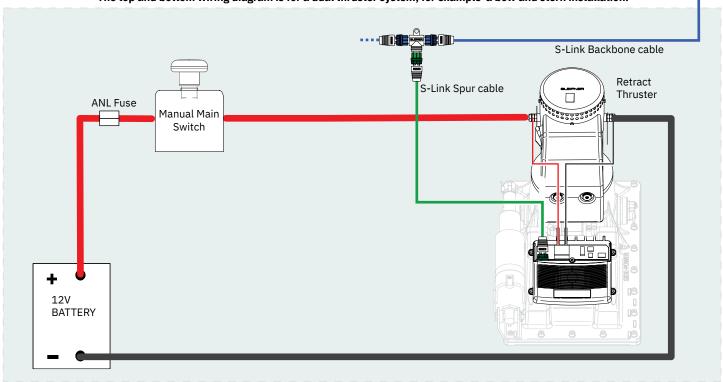
Motor lug connection



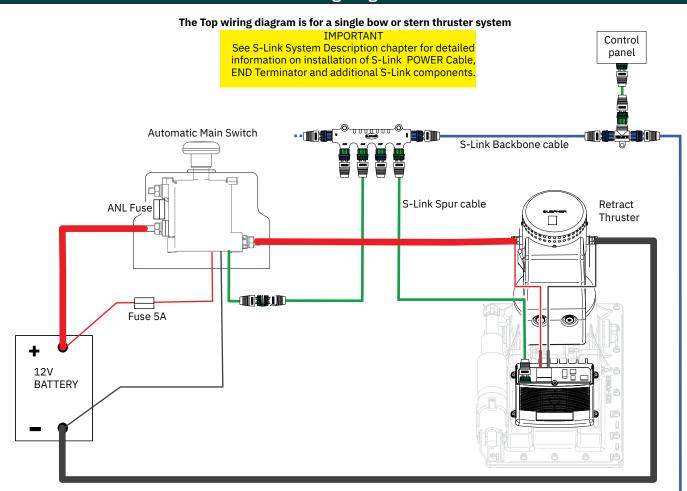
Manual main switch wiring diagram 12V retract thruster



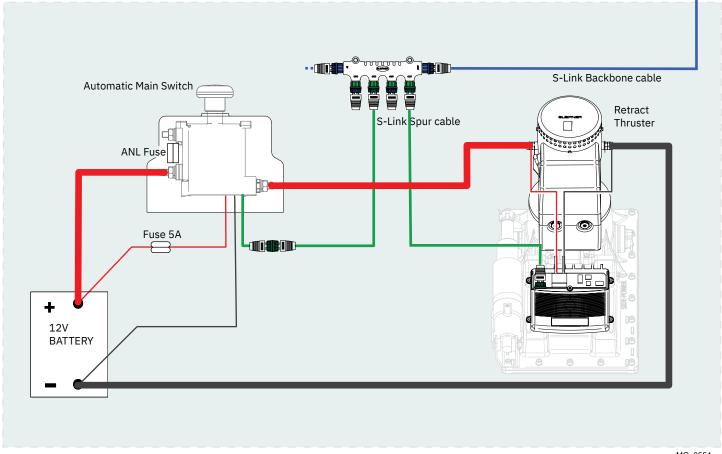
The top and bottom wiring diagram is for a dual thruster system, for example a bow and stern installation.



Automatic main switch wiring diagram 12V retract thruster

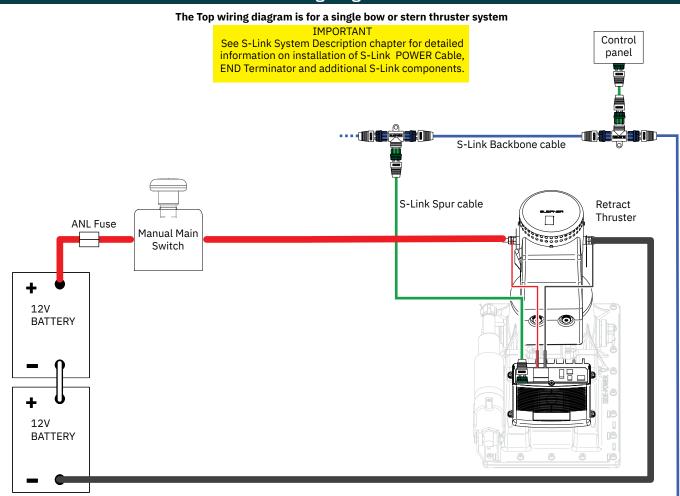


The top and bottom wiring diagram is for a dual thruster system, for example a bow and stern installation.

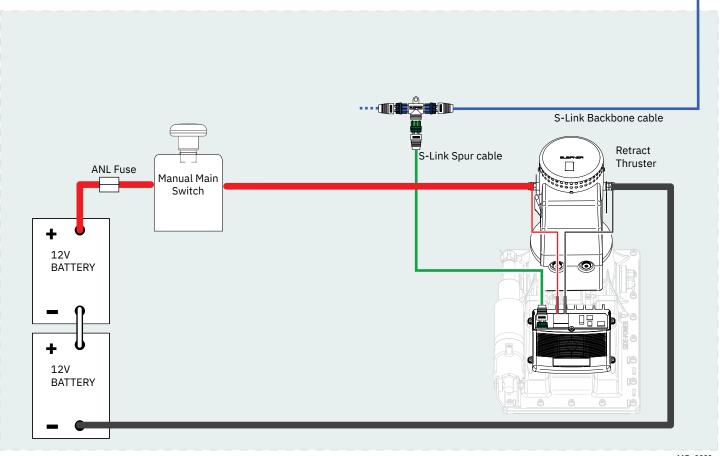


MG_0554

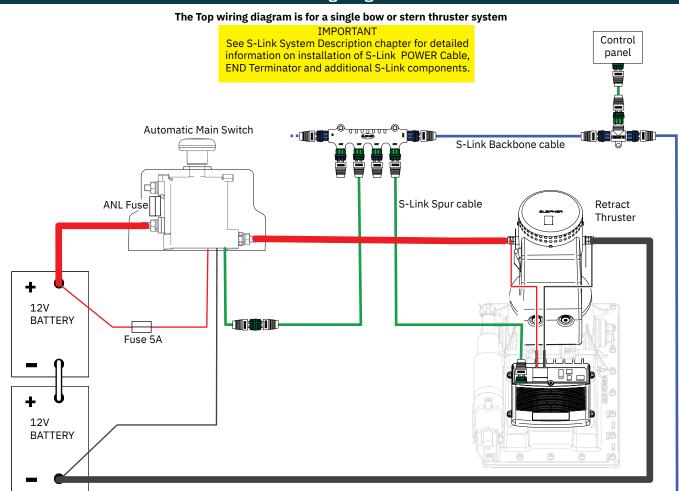
Manual main switch wiring diagram 24V retract thruster



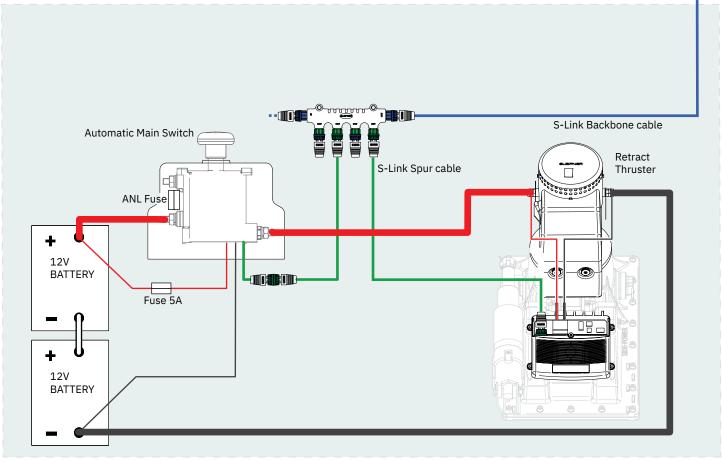
The top and bottom wiring diagram is for a dual thruster system, for example a bow and stern installation.



Automatic main switch wiring diagram 24V retract thruster



The top and bottom wiring diagram is for a dual thruster system, for example a bow and stern installation.



MG_0628

S-Link system description

S-Link is a CAN-based control system used for communication between Sleipner products installed on a vessel. The system uses BACKBONE Cables as a common power and communication bus with separate SPUR Cables to each connected unit. Only one S-Link POWER cable shall be connected to the BACKBONE Cable. Units with low power consumption are powered directly from the S-Link bus.

Main advantages of S-Link system:

- Compact and waterproof plugs.
- BACKBONE and SPUR Cables have different colour coding and keying to ensure correct and easy installation. BACKBONE Cables have blue connectors and SPUR Cables have green connectors.
- Different cable lengths and BACKBONE Extenders make the system scalable and flexible to install.

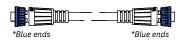
Installation of S-Link cables:

Select appropriate cables to keep the length of BACKBONE- and SPUR Cables to a minimum. In case of planned installation with total BACKBONE Cable length exceeding 100 meters please consult your local distributor. The S-Link cables should be properly fastened when installed to avoid sharp bend radius, cable chafing and undesired strain on connectors. Locking mechanism on connectors must be fully closed. To ensure long lifetime, cables, T-Connectors and Extenders should not be located so that they are permanently immersed in water or other fluids. It is also recommended to install cables such that water and condensation do not run along the cables and into the connectors.

The POWER Cable should ideally be connected around the middle of the BACKBONE bus to ensure an equal voltage drop at each end of the BACKBONE Cable. The yellow and black wire in the POWER Cable shall be connected to GND and the red wire connected to +12VDC or +24VDC.

To reduce the risk of interference, avoid routing the S-Link cables close to equipment such as radio transmitters, antennas or high voltage cables. The backbone must be terminated at each end with the END Terminator.

SPUR cables can be left unterminated to prepare for the installation of future additional equipment. In such cases, ensure to protect open connectors from water and moisture to avoid corrosion in the connectors.



*Green end

BACKBONE Cable

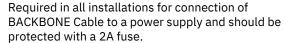
Forms the communication and power bus throughout a vessel. Available in different standard lengths.

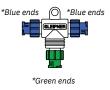




Used to connect S-Link compliant products to the backbone cable. One SPUR Cable must be used for each connected component, with no exceptions. Recommended to be as short as practically possible. Available in different standard lengths.

POWER Cable





T-Connector

Used for connection of SPUR or POWER Cable to the BACKBONE Cable. One T-Connector for each connected cable.



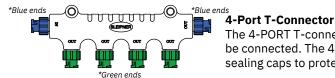
BACKBONE Extender

Connects two BACK-**BONE Cables to extend** the length.



END Terminator

Must be one at each end of the BACKBONE bus.



The 4-PORT T-connector allows multiple SPUR Cables to be connected. The 4-PORT T-connector comes with two

sealing caps to protect unused ports.

S-Link installation example Control Panel **Control Panel** Spu 4 Port T-Connecto 4 Port T-Connector Backbone Extender T-Connecto O TOTOLO End Backbone Backbone Backbone Terminator S-Link Automatic -**Power Supply** Main switch Yellou Red_ ∃^{12/24}V Spui Switch Optional Fuse 2A *For DC system **Bow Thruster** Stern Thruster MG 0159 9pt

IMPORTANT

Before the thruster motor is operated, check the drive shaft alignment is completely straight when it reaches the end position form the control panel operation:

- 1) Connect power to thruster and S-link system.
- 2) Sett DIP-switch on the controller to 0000.
- 3) Turn on the panel. (The thruster deploys.)
- 4) The actuator lever arm is set to alignment marking on the nut
- 5) If marks align, turn panel off. The thruster retracts.
- 6) If the marks do not align, proceed to calibrate drive shaft.

Calibrate drive shaft alignment

MC_0069

(NB: The drive shaft is correctly aligned when manufactured)

- 1) With dip-switches select 'Service Mode'.
- 2) Align the arrow on the actuator arm with the calibration mark, using the UP/DOWN buttons.
- 3) With dip-switches select 'Sensor Calibration Mode'.
- 4) Press and hold both UP and DOWN buttons until STATUS LED light up green.

(NB: If FAULT LED light-up red, then the calibration is out of position (wrong align mark).

5) With dip-switches select 'Operation Mode', thruster retracts.

Actuator configuration

MC_0069

Dip-switch number 1 & 2 configures the actuator(s).

No.1 set to OFF when the retract has two actuators.

No.1 set to ON when the retract only has one actuator.

No.2 set to OFF when the retract does not have P8 type actuator(s).

No.2 set to ON when the retract has the P8 type actuator(s).

If dip-switch no.2 is set to ON and the actuator gives a rattling noise when the door closes, then there probably is not P8 actuator(s) and dip-switch no.2 needs to be set to OFF.

The actuator is a P8 type:

- -If the actuator has a plastic cap at the back where you can adjust the actuator manually.
- -If it is marked with a sticker with P8
- -If the manufacturer label says P8

LED indication

MC_0069

Continuous red light:

Motor over-temp, Controller over-temp, Controller no communication, Motor relay failure, Low battery voltage, Position sensor failure, No power to actuators, Retractable unit failure, Temp sensor open circuit.

Flashing red light:

Red light fast blinking: Dip-switch in an invalid position.

Red light short flash every 2 seconds: Shaft not calibrated, or shaft calibrated out of range.

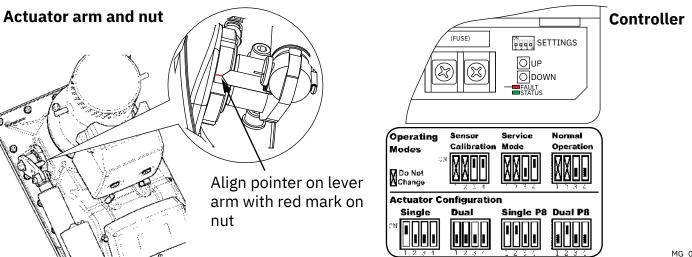
Continuous green light:

Normal mode, Service mode (actuators operated by UP/DOWN buttons).

Re-calibrated "down"-position.

Flashing green light:

No S-Link communication.



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Doct	inctal	lation c	600	dict
			1112191	

MC_0033

[] The bolts holding the gear leg and main bracket together are tightened correctly.
[] The bolts holding the motor to its bracket are tightened correctly.
[] All electrical connections are clean, dry and tight, and the correct cable, fuse and main switch size.
[] Check that there is no electrical connection between the electro motor body and positive terminal on the motor, and between the electro motor body and the negative terminal on the motor with an ohm meter.
[] Anti-fouling has been applied to the gear leg and propeller but NOT anodes, sealing/rubber fittings or propeller shafts.
[] Propeller is fastened correctly to the shaft.
[] Propeller turns freely in tunnel.
[] The anode and/ or holding screw is tightened well with thread glue.
[] Check the boat for potential water leakage around installation areas.
[] Correct drive direction as per control panel.
[] User Manual is supplied to the owner.
The thruster has been installed as per the instructions in this manual and all points in checklist above have been controlled.
Signed:
Date:
Date: Thruster type:
Thruster type:

Find your local professional dealer from our certified worldwide network for expert service and support. visit our website www.sleipnergroup.com/support

Product spare parts and additional resources

MC 0024

For additional supporting documentation, we advise you to visit our website www.sleipnergroup.com and find your Sleipner product.

Warranty statement

MC_0024

- Sleipner Motor AS (The "Warrantor") warrants that the equipment (parts, materials, and embedded software of products) manufactured by the Warrantor is free from defects in workmanship and materials for purpose for which the equipment is intended and under normal use and maintenance service (the "Warranty").
- 2. This Warranty is in effect for two years (Leisure Use) or one year (Commercial and other Non-leisure Use) from the date of delivery/purchase by the end user, with the following exceptions;
 - (a) For demonstration vessels, or vessels kept on the water, the dealer is considered as the end user from 6 months after their launch of the vessel;
 - (b) The warranty period starts no later than 18 months after the first launch of the vessel.
 - Please note that the boat manufacturer and dealer must pay particular attention to correct maintenance and service both by the products manuals as well as general good practice for the location the boat is kept in the period the boat is in their care. In cases where the 6 and 18 months grace periods for boat builders and dealers are passed, it is possible to obtain a full warranty upon inspection and approval of the warrantor or such representative.
- 3. Certain parts, classified as wearable or service parts, are not covered by the warranty. A failure to follow the required maintenance and service work as described in the product manual render all warranty on parts or components directly or indirectly affected by this void. Please also note that for some parts, time is also a factor separately from actual operational hours.
- 4. This Warranty is transferable and covers the equipment for the specified warranty period.
- 5. The warranty does not apply to defects or damages caused by faulty installation or hook-up, abuse or misuse of the equipment including exposure to excessive heat, salt or fresh water spray, or water immersion except for equipment specifically designed as waterproof.
- 6. In case the equipment seems to be defective, the warranty holder (the "Claimant") must do the following to make a claim:

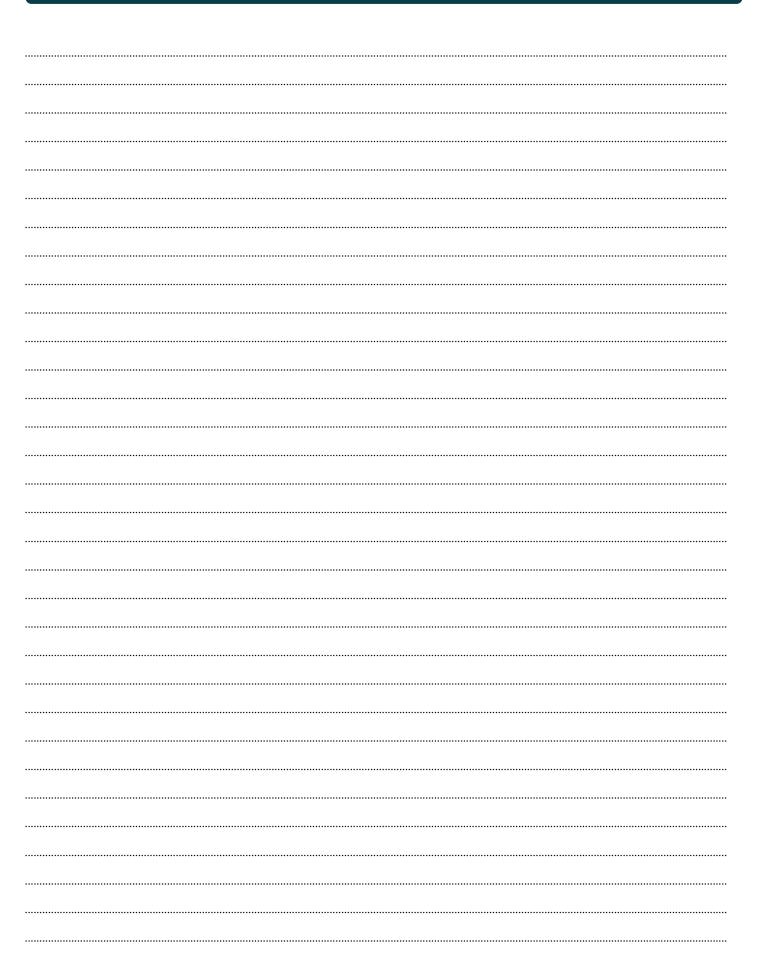
 (a) Contact the dealer or service centre where the equipment was purchased and make the claim. Alternatively, the Claimant can make the claim to a dealer or service centre found at www.sleipnergroup.com. The Claimant must present a detailed written statement of the nature and circumstances of the defect, to the best of the Claimant's knowledge, including product identification and serial nbr., the date and place of purchase and the name and address of the installer. Proof of purchase date should be included with the claim, to verify that the warranty period has not expired:
 - (b) Make the equipment available for troubleshooting and repair, with direct and workable access, including dismantling of furnishings or similar, if any, either at the premises of the Warrantor or an authorised service representative approved by the Warrantor. Equipment can only be returned to the Warrantor or an authorised service representative for repair following a pre-approval by the Warrantor's Help Desk and if so, with the Return Authorisation Number visible postage/shipping prepaid and at the expense of the Claimant.
- 7. Examination and handling of the warranty claim:
 - (a) If upon the Warrantor's or authorised service Representative's examination, the defect is determined to result from defective material or workmanship in the warranty period, the equipment will be repaired or replaced at the Warrantor's option without charge, and returned to the Purchaser at the Warrantor's expense. If, on the other hand, the claim is determined to result from circumstances such as described in section 4 above or a result of wear and tear exceeding that for which the equipment is intended (e.g. commercial use of equipment intended for leisure use), the costs for the troubleshooting and repair shall be borne by the Claimant;
 - (b) No refund of the purchase price will be granted to the Claimant, unless the Warrantor is unable to remedy the defect after having a reasonable number of opportunities to do so. In the event that attempts to remedy the defect have failed, the Claimant may claim a refund of the purchase price, provided that the Claimant submits a statement in writing from a professional boating equipment supplier that the installation instructions of the Installation and Operation Manual have been complied with and that the defect remains.
- 8. Warranty service shall be performed only by the Warrantor, or an authorised service representative, and any attempt to remedy the defect by anyone else shall render this warranty void.
- 9. No other warranty is given beyond those described above, implied or otherwise, including any implied warranty of merchantability, fitness for a particular purpose other than the purpose for which the equipment is intended, and any other obligations on the part of the Warrantor or its employees and representatives.
- 10. There shall be no responsibility or liability whatsoever on the part of the Warrantor or its employees and representatives based on this Warranty for injury to any person or persons, or damage to property, loss of income or profit, or any other incidental, consequential or resulting damage or cost claimed to have been incurred through the use or sale of the equipment, including any possible failure or malfunction of the equipment or damages arising from collision with other vessels or objects.
- 11. This warranty gives you specific legal rights, and you may also have other rights which vary from country to country.

Patents

MC_0024

At Sleipner we continually reinvest to develop and offer the latest technology in marine advancements. To see the many unique designs we have patented visit our website www.sleipnergroup.com/patents

Notes	MC_0037



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Learn more about our products at www.sleipnergroup.com



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Made in Norway